

PSIET, KARANDA, DHENKANAL

LESSONPLAN Session(2022-2023)

Discipline: Electrical Engg.	Semester: 6 th , Summer/2023	Name of the Faculty: Nabin Kumar Pradhan, Lecturer
Subject: Control Systems Engineering Theory-3	No.of Days/week: 05	StartDate: 15/02/2023 End Date: 23/05/2023

Week	Class Day	Theory Topics
1st	1st	Classification of Control system.
	2nd	Open loop system & Closed loop system and its comparison.
	3rd	Effects of Feedback.
	4th	Standard test signals (Step, Ramp, Parabolic, and Impulse Functions).
	5th	Standard test signals (Step, Ramp, Parabolic, and Impulse Functions).
2nd	1st	Servo mechanism.
	2nd	Regulators (Regulating systems)
	3rd	Revision and Doubt clearing.
	4th	Transfer Function of a system.
	5th	Transfer Function of a system.
3rd	1st	Impulse response of a system.
	2nd	Properties, Advantages & Disadvantages of Transfer Function.
	3rd	Poles & Zeros of transfer Function.
	4th	Representation of poles & Zero on the s-plane.
	5th	Representation of poles & Zero on the s-plane.
4th	1st	Simple problems of transfer function of network.
	2nd	Doubt clearing and Class test.

	3dr	Closetlooptransferfunction.
	4th	Conceptofcharacteristicsequeation
	5th	Conceptofcharacteristicsequeation
5th	1st	BlockDiagramreductiontechnique.
	2nd	BlockDiagramreductiontechnique.
	3rd	Stabilityofsystem.
	4th	Blockdiagramreductionproblem.
	5th	BlockDiagramreductiontechnique
6th	1st	ModelingofElectricalSystems(R,L,C,Analogoussystem).
	2nd	RevisionandDoubtclearing.
	3rd	DefinitionofBasicElementsofaBlockDiagram.
	4th	CanonicalFormofClosedloopSystems.
	5th	CanonicalFormofClosedloopSystems.
7th	1st	RulesforBlockdiagramReductionpart-I
	2nd	RulesforBlockdiagramReductionpart-II
	3rd	ProcedureforofReductionofBlockDiagram.
	4th	SimpleProblemforequivalenttransferfunction.
	5th	SimpleProblemforequivalenttransferfunction.
8th	1st	BasicDefinitioninSFG&properties.
	2nd	Mason'sGainformula.
	3rd	StepsforsolvingSignalflowGraph.
	4th	SimpleproblemsinSignalflowgraphfornetwork.
	5th	SimpleproblemsinSignalflowgraphfornetwork.
9th	1st	DoubtclearingandClasstest.
	2nd	DefinitionofTime,Stability,steady-stateresponse,accuracy,transient accuracy, In-sensitivity and robustness.
	3rd	SystemTimeResponse.
	4th	Frequencyresponseanalysis.
	5th	AnalysisofSteadyStateError.

10th	1st	Types of Input & Steady state Error (Step, Ramp, Parabolic).
	2nd	Parameters of first order system & second-order systems.
	3rd	Derivation of time response Specification (Delay time, Rise time, Peak time, Settling time, Peak overshoot).
	4th	Revision and Doubt clearing.
	5th	Revision and Doubt clearing.
	11th	1st
2nd		Introduction to Basic control Action & Basic modes of feedback control: proportional, integral and derivative.
3rd		Effect of feedback on overall gain, Stability.
4th		Realization of Controllers (P, PI, PD, PID) with OPAMP.
5th		Realization of Controllers (P, PI, PD, PID) with OPAMP
12th	1st	Revision and Doubt clearing.
	2nd	Effect of location of poles on stability.
	3rd	Routh-Hurwitz stability criterion.
	4th	Steps for Root locus method.
	5th	Steps for Root locus method.
13th	1st	Root locus method of design (Simple problem).
	2nd	Revision and Doubt clearing.
	3rd	Frequency response, Relationship between time & frequency response.
	4th	Methods of Frequency response.
	5th	Methods of Frequency response.
14th	1st	Polar plots & steps for polar plot.
	2nd	Bode plot & steps for Bode plots.
	3rd	Stability in frequency domain, Gain Margin & Phase margin.
	4th	Nyquist plots. Nyquist stability criterion.
	5th	Nyquist plots. Nyquist stability criterion.
15th	1st	Simple problems as above.
	2nd	Concepts of state, state variable, state model.

3rd	State models for linear continuous time functions (Simple).
4th	Doubt clearing and Class test.
5th	Doubt clearing and Class test.

Nabin Kumar Bhandari

Signature of the faculty

12/12/23

Signature of the Principal